

Linear Algebra with Dirac notation

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Note Title

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Vectors are equivalent to states in quantum mechanics : $|\alpha\rangle, |\beta\rangle, |\gamma\rangle, \dots$

scalars : $a, b, c, \dots$ i complex numbers

Vector addition and scalar multiplication follows the common rules such as

① commutative-ness : $|\alpha\rangle + |\beta\rangle = |\beta\rangle + |\alpha\rangle$

② associative-ness : $|\alpha\rangle + (|\beta\rangle + |\gamma\rangle) = (|\alpha\rangle + |\beta\rangle) + |\gamma\rangle$

③ distributive-ness : $a(|\alpha\rangle + |\beta\rangle) = a|\alpha\rangle + a|\beta\rangle$

④ associative-ness : $a(b|\alpha\rangle) = (ab)|\alpha\rangle$

⑤ $|\alpha\rangle + |0\rangle = |\alpha\rangle$

⑥ $|\alpha\rangle + |- \alpha\rangle = |0\rangle$

⑦ $0|\alpha\rangle = |0\rangle$

⑧ $1|\alpha\rangle = |\alpha\rangle$

⑨ $|- \alpha\rangle = (-1)|\alpha\rangle$

* linear combination of $|\alpha\rangle, |\beta\rangle, |\gamma\rangle, \dots$ is

$$a|\alpha\rangle + b|\beta\rangle + c|\gamma\rangle + \dots$$

* $|\alpha\rangle$ is linearly independent of the set $|\alpha\rangle, |\beta\rangle, |\gamma\rangle, \dots$ if it cannot be written as a linear combination of them

Ex. $\hat{k}$ is linearly independent of $\hat{i}$ and $\hat{j}$ but any vector in the xy plane is linearly dependent on $\hat{i}$ and $\hat{j}$

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* If every vector can be written as a linear combination of a set of vectors, this set is said to **span** the space.

* A set of linearly independent vectors that span the space is called a **basis**.

* The number of vectors in any basis is called the **dimension**.

* With a basis $\{|e_1\rangle, |e_2\rangle, \dots, |e_n\rangle\}$, if

$$|\alpha\rangle = a_1|e_1\rangle + a_2|e_2\rangle + \dots + a_n|e_n\rangle,$$

$$|\alpha\rangle \leftrightarrow \begin{pmatrix} a_1 \\ \vdots \\ a_n \end{pmatrix}$$

$a_1, a_2, \dots, a_n$ are called **components**.

Then $|\alpha\rangle + |\beta\rangle \leftrightarrow \begin{pmatrix} a_1 + b_1 \\ \vdots \\ a_n + b_n \end{pmatrix}$

$$c|\alpha\rangle \leftrightarrow \begin{pmatrix} ca_1 \\ \vdots \\ ca_n \end{pmatrix}$$

Inner Products

With orthonormal basis $\{|e_1\rangle, |e_2\rangle, \dots, |e_n\rangle\}$, that is $\langle e_i | e_j \rangle = \delta_{ij}$

$$|\alpha\rangle \leftrightarrow \begin{pmatrix} a_1 \\ \vdots \\ a_n \end{pmatrix}, \quad |\beta\rangle \leftrightarrow \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix}$$

$\langle \alpha | \equiv (|\alpha\rangle)^\dagger = (a_1^*, \dots, a_n)$ is called **bra** vector

, while $|\alpha\rangle$ is called **ket** vector

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$$\text{And } \langle \alpha | \beta \rangle = (a_1^*, \dots, a_n^*) \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix}$$

$$= a_1^* b_1 + a_2^* b_2 + \dots + a_n^* b_n$$

This is called the inner product.

- $\langle \beta | \alpha \rangle = \langle \alpha | \beta \rangle^*$
- $\langle \alpha | (b|\beta\rangle + c|\gamma\rangle) = b\langle \alpha | \beta \rangle + c\langle \alpha | \gamma \rangle$
- $\|\alpha\| = \sqrt{\langle \alpha | \alpha \rangle}$: **norm** of $|\alpha\rangle$
 $= \sqrt{|a_1|^2 + |a_2|^2 + \dots + |a_n|^2}$
- $a_i = \langle e_i | \alpha \rangle$

* Analogy with ordinary vectors

$$\vec{a} \cdot \vec{b} = \|\vec{a}\| \|\vec{b}\| \cos \theta$$

$$\langle \alpha | \beta \rangle = \|\alpha\| \|\beta\| \cos \theta \quad ? \quad \text{No!}$$

$$\text{But still, } |\langle \alpha | \beta \rangle|^2 = \|\alpha\|^2 \|\beta\|^2 \cos^2 \theta$$

$$\Leftrightarrow \langle \alpha | \beta \rangle \langle \beta | \alpha \rangle = \langle \alpha | \alpha \rangle \langle \beta | \beta \rangle \cos^2 \theta$$

$$\Rightarrow \sqrt{|\langle \alpha | \beta \rangle|^2} = \|\alpha\| \|\beta\| \cos \theta$$

$$\therefore |\langle \alpha | \beta \rangle|^2 \leq \langle \alpha | \alpha \rangle \langle \beta | \beta \rangle$$

Called Schwarz inequality

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* Gram - Schmidt Procedure to find an orthonormal basis

$$\boxed{\text{Ex}} \quad |\psi_a\rangle = |\psi_1\rangle + 2i|\psi_2\rangle$$

$$|\psi_b\rangle = i|\psi_1\rangle + |\psi_2\rangle$$

with $|e'_1\rangle \equiv \frac{|\psi_a\rangle}{\|\psi_a\|}$, find $|e_2\rangle$

orthonormal to $|e'_1\rangle$ using the Gram-Schmidt procedure

Ans: $|e_2\rangle = |\psi_b\rangle - \langle e'_1 | \psi_b \rangle |e'_1\rangle$

$$|e'_2\rangle = \frac{|e_2\rangle}{\|e_2\|}$$

$$|\psi_a\rangle = \begin{pmatrix} 1 \\ 2i \end{pmatrix} \Rightarrow \|\psi_a\| = \sqrt{5}$$

$$|\psi_b\rangle = \begin{pmatrix} i \\ 1 \end{pmatrix}$$

$$\Rightarrow |e'_1\rangle = \frac{1}{\sqrt{5}} \begin{pmatrix} 1 \\ 2i \end{pmatrix}$$

$$|e_2\rangle = \begin{pmatrix} i \\ 1 \end{pmatrix} - \left[\frac{1}{\sqrt{5}} (1, -2i) \begin{pmatrix} i \\ 1 \end{pmatrix} \right] \cdot \frac{1}{\sqrt{5}} \begin{pmatrix} 1 \\ 2i \end{pmatrix}$$

$$= \begin{pmatrix} i \\ 1 \end{pmatrix} - \frac{1}{5} [i - 2i] \begin{pmatrix} 1 \\ 2i \end{pmatrix}$$

$$= \begin{pmatrix} i \\ 1 \end{pmatrix} - \frac{1}{5} \begin{pmatrix} -i \\ 2 \end{pmatrix} = \frac{1}{5} \begin{pmatrix} 5i + i \\ 5 - 2 \end{pmatrix}$$

$$= \frac{3}{5} \begin{pmatrix} 2i \\ 1 \end{pmatrix}$$

$$\Rightarrow |e'_2\rangle = \frac{1}{\sqrt{5}} \begin{pmatrix} 2i \\ 1 \end{pmatrix}$$

$$\therefore |e_1'\rangle = \frac{1}{\sqrt{5}} (|\psi_1\rangle + 2i|\psi_2\rangle)$$

$$|e_2'\rangle = \frac{1}{\sqrt{5}} (2i|\psi_1\rangle + |\psi_2\rangle)$$

Double check $\langle e_2' | e_1' \rangle = \frac{1}{5} (-2i, 1) \begin{pmatrix} 1 \\ 2i \end{pmatrix}$

$$= \frac{1}{5} (-2i + 2i) = 0$$

Matrices

Matrix is equivalent to operator in Quantum mechanics

$$|\beta\rangle = T|\alpha\rangle \Leftrightarrow \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix} = \begin{pmatrix} T_{11} & T_{12} & \dots & T_{1n} \\ T_{21} & & & \\ \vdots & \ddots & & \\ T_{2n} & & & T_{nn} \end{pmatrix} \begin{pmatrix} a_1 \\ \vdots \\ a_n \end{pmatrix}$$

with $T_{ij} = \langle e_i | T | e_j \rangle$

* Transpose: $\tilde{T} \equiv \begin{pmatrix} T_{11} & T_{21} & \dots & T_{2n} \\ T_{12} & & & \\ \vdots & \ddots & & \\ T_{1n} & & & T_{nn} \end{pmatrix}$

* Hermitian conjugate of "T" is

$$T^\dagger \equiv (\tilde{T})^* = \begin{pmatrix} T_{11}^* & T_{21}^* & \dots & T_{2n}^* \\ T_{12}^* & & & \\ \vdots & \ddots & & \\ T_{1n}^* & & & T_{nn}^* \end{pmatrix}$$

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This definition of hermitian conjugate applies to vectors as well so that

$$|\alpha\rangle = \begin{pmatrix} a_1 \\ \vdots \\ a_n \end{pmatrix} \Rightarrow \langle\alpha| = [|\alpha\rangle]^* = (a_1^* \dots a_n^*)$$

Thus

$$\langle\alpha|\beta\rangle = (a_1^* \dots a_n^*) \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix}$$

* If $T^\dagger = T$, T is called hermitian

* Generally, matrix multiplication is not commutative, that is,

$$T \cdot S \neq S \cdot T$$

* Commutator is defined as

$$[S, T] = ST - TS$$

* $(ST)^\dagger = T^\dagger S^\dagger$

* Identity matrix $I \equiv \begin{pmatrix} 1 & & 0 \\ & \ddots & \\ 0 & & 1 \end{pmatrix}$

* Inverse matrix T^{-1} ; $T \cdot T^{-1} = T^{-1} \cdot T = I$

$$T^{-1} = \frac{1}{\det T} \cdot \tilde{C}, \text{ with } C \text{ the matrix of cofactors}$$

$\Rightarrow$ If $\det T = 0$, T^{-1} does not exist and T is called singular

* $(ST)^{-1} = T^{-1} \cdot S^{-1}$

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Ex. $T = \begin{pmatrix} 1 & 0 & \bar{i} \\ 0 & 2 & 0 \\ 2\bar{i} & 0 & 1 \end{pmatrix}$

$$\det T = 1 \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} - 0 \begin{vmatrix} 0 & 0 \\ 2\bar{i} & 1 \end{vmatrix} + \bar{i} \begin{vmatrix} 0 & 2 \\ 2\bar{i} & 0 \end{vmatrix}$$

$$= 2 + \bar{i}(-4\bar{i}) = 2 + 4 = 6$$

$$C = \begin{pmatrix} \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix}, -\begin{vmatrix} 0 & 0 \\ 2\bar{i} & 1 \end{vmatrix}, \begin{vmatrix} 0 & 2 \\ 2\bar{i} & 0 \end{vmatrix} \\ -\begin{vmatrix} 0 & \bar{i} \\ 0 & 1 \end{vmatrix}, \begin{vmatrix} 1 & \bar{i} \\ 2\bar{i} & 1 \end{vmatrix}, -\begin{vmatrix} 1 & 0 \\ 2\bar{i} & 0 \end{vmatrix} \\ \begin{vmatrix} 0 & \bar{i} \\ 2 & 0 \end{vmatrix}, -\begin{vmatrix} 1 & \bar{i} \\ 0 & 0 \end{vmatrix}, \begin{vmatrix} 1 & 0 \\ 0 & 2 \end{vmatrix} \end{pmatrix}$$

$$= \begin{pmatrix} 2 & 0 & -4\bar{i} \\ 0 & 1+2 & 0 \\ -2\bar{i} & 0 & 2 \end{pmatrix} = \begin{pmatrix} 2 & 0 & -4\bar{i} \\ 0 & 3 & 0 \\ -2\bar{i} & 0 & 2 \end{pmatrix}$$

$$\therefore T^{-1} = \frac{\tilde{C}}{\det T} = \frac{1}{6} \begin{pmatrix} 2 & 0 & -2\bar{i} \\ 0 & 3 & 0 \\ -4\bar{i} & 0 & 2 \end{pmatrix}$$

Check $\begin{pmatrix} 1 & 0 & \bar{i} \\ 0 & 2 & 0 \\ 2\bar{i} & 0 & 1 \end{pmatrix} \cdot \frac{1}{6} \begin{pmatrix} 2 & 0 & -2\bar{i} \\ 0 & 3 & 0 \\ -4\bar{i} & 0 & 2 \end{pmatrix}$

$$= \frac{1}{6} \begin{pmatrix} 2+4 & 0 & -2\bar{i}+2\bar{i} \\ 0 & 6 & 0 \\ 4\bar{i}-4\bar{i} & 0 & 4+2 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} //$$

Eigenvectors and eigenvalues

$T|\alpha\rangle$ is like rotating the vector $|\alpha\rangle$ and multiplying by a scalar onto it.

- Special set of vectors that remain unchanged in this process except for a constant factor are called "eigenvectors".

That is, if $T|\alpha\rangle = \lambda|\alpha\rangle$,

$|\alpha\rangle$ is called eigenvector and λ is called the eigenvalue corresponding to the eigenvector

* How to find $|\alpha\rangle$ and λ ?

$$T|\alpha\rangle = \lambda|\alpha\rangle \Rightarrow (T - I \cdot \lambda)|\alpha\rangle = 0$$

This will have non-zero solution for $|\alpha\rangle$ only if $\det(T - I\lambda) = 0$. Otherwise $T - I\lambda$ will have an inverse matrix and $|\alpha\rangle$ will be zero.

Ex1

$$T = \begin{pmatrix} 2 & 0 & -2 \\ -2i & i & 2i \\ 1 & 0 & -1 \end{pmatrix}$$

Find eigenvectors and eigenvalues

$$\det \begin{vmatrix} 2-\lambda & 0 & -2 \\ -2i & i-\lambda & 2i \\ 1 & 0 & -1-\lambda \end{vmatrix} = 0$$

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$$\Rightarrow (2-\lambda)(-(\bar{z}-\lambda)(1+\lambda)) - 2(-(\bar{z}-\lambda)) = 0$$

$$\Rightarrow (\bar{z}-\lambda)((2-\lambda)(1+\lambda) - 2) = 0$$

$$\Rightarrow (\bar{z}-\lambda)(\cancel{2} - \lambda + 2\lambda - \lambda^2 - \cancel{2}) = 0$$

$$\Rightarrow (\bar{z}-\lambda)(\lambda - \lambda^2) = 0$$

$$\Rightarrow \lambda(1-\lambda)(\bar{z}-\lambda) = 0$$

$$\lambda = 0, 1, \bar{z}$$

For $\lambda = 0$

$$\begin{pmatrix} 2 & 0 & -2 \\ -2\bar{z} & \bar{z} & 2\bar{z} \\ 1 & 0 & -1 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = 0$$

$$\Rightarrow 2a - 2c = 0 \Rightarrow c = a$$

$$-2\bar{z} \cdot a + \bar{z}b + 2\bar{z}c = 0$$

$$\Rightarrow -2a + b + 2a = 0 \Rightarrow b = 0$$

$$\Rightarrow \begin{pmatrix} a \\ b \\ c \end{pmatrix} = a \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \Rightarrow \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$$

with normalization

For $\lambda = 1$

$$\begin{pmatrix} 2-1 & 0 & -2 \\ -2\bar{z} & \bar{z}-1 & 2\bar{z} \\ 1 & 0 & -1-1 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = 0$$

$$\Rightarrow a - 2c = 0, \Rightarrow a = 2c$$

$$-2\bar{z}a + (\bar{z}-1)b + 2\bar{z}c = 0$$

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$$\Rightarrow -4\bar{c} + (\bar{c}-1)b + 2\bar{c}c = 0$$

$$\Rightarrow b = \frac{2\bar{c}}{\bar{c}-1} = \frac{2\bar{c}(\bar{c}+1)}{(\bar{c}-1)(\bar{c}+1)} c$$

$$= \frac{2(-1+\bar{c})}{-2} c = (1-\bar{c})c$$

$$\Rightarrow \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} 2 \\ 1-\bar{c} \\ 1 \end{pmatrix} c = \frac{1}{\sqrt{7}} \begin{pmatrix} 2 \\ 1-\bar{c} \\ 1 \end{pmatrix}$$

with normalization

For $\lambda = \bar{c}$

$$\begin{pmatrix} 2-\bar{c} & 0 & -2 \\ -2\bar{c} & 0 & 2\bar{c} \\ 1 & 0 & -1-\bar{c} \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = 0$$

$$\Rightarrow (2-\bar{c})a - 2c = 0$$

$$-2\bar{c}a + 2\bar{c}c = 0 \Rightarrow c = a$$

$$a - (1+\bar{c})c = 0$$

$$\Rightarrow [(2-\bar{c}) - 2]a = 0 \Rightarrow a = 0$$

$$\Rightarrow \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} 0 \\ b \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \text{ with normalization}$$

If you use these eigenvectors as a new basis, in this new basis, the matrix appears as diagonalized.

In other words, with $|e_1\rangle = |\alpha_{\lambda=0}\rangle$

$|e_2\rangle = |\alpha_{\lambda=1}\rangle$ and $|e_3\rangle = |\alpha_{\lambda=\bar{c}}\rangle$
as the new basis,

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$$|\alpha_{\lambda=0}\rangle = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \quad |\alpha_{\lambda=1}\rangle = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

$$\text{and } |\alpha_{\lambda=2}\rangle = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}.$$

And in this new basis

$$T_{\text{old}} = \begin{pmatrix} 2 & 0 & -2 \\ -2i & i & 2i \\ 1 & 0 & -1 \end{pmatrix} \Rightarrow T_{\text{new}} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & i \end{pmatrix}.$$

* Every hermitian matrix is diagonalizable